

# CAS 741, CES 741 (Development of Scientific Computing Software)

Fall 2017

## 05 Program Families DRAFT

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September 15, 2017



# Program Families

- Administrative details
- Questions?
- License and copyright
- Motivation
- Proposed Family Methods
- Family of Mesh Generators
- Family of Linear Solvers
- Family of Material Behaviour Models

# Administrative Details

- Add me to your GitHub repos, my GitHub id is smiths
- Assign me an issue to review your problem statements
  - ▶ Clearly state that you would like me to review your problem statement
  - ▶ Include a link to your problem statement
- Updates to SRS template
- Commonality analysis should start from SRS template
- Presentations
  - ▶ VGA by default, ask if need adapter
  - ▶ Can you my laptop

# Administrative Details: Deadlines

<b>Problem Statement</b>	Week 02	Sept 15
<b>SRS Present</b>	Week 04	Week of Sept 25
<b>SRS</b>	Week 05	Oct 4
V&V Present	Week 06	Week of Oct 16
V&V Plan	Week 07	Oct 25
MG Present	Week 08	Week of Oct 30
MG	Week 09	Nov 8
MIS Present	Week 10	Week of Nov 13
MIS	Week 11	Nov 22
Impl. Present	Week 12	Week of Nov 27
Final Documentation	Week 13	Dec 6

# Questions?

- Questions about ...

# Specification Qualities

- What are the important qualities for a specification?

# Specification Qualities

- The qualities we previously discussed (usability, maintainability, reusability, verifiability etc.)
- Clear, unambiguous, understandable
- Consistent
- Complete
  - ▶ Internal completeness
  - ▶ External completeness
- Incremental
- Validatable
- Abstract
- Traceable

Summarized in [24, p. 406]

# Clear, Unambiguous, Understandable

- Specification fragment for a word-processor
  - ▶ Selecting is the process of designating areas of the document that you want to work on. Most editing and formatting actions require two steps: first you select what you want to work on, such as text or graphics; then you initiate the appropriate action.
- What are the potential problems with this specification?



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- What are the potential problems with this specification?
  - ▶ Can an area be scattered?
  - ▶ Can both text and graphics be selected?

# Clear, Unambiguous, Understandable

- Specification fragment from a real safety-critical system
  - ▶ The message must be triplicated. The three copies must be forwarded through three different physical channels. The receiver accepts the message on the basis of a two-out-of-three voting policy.
- What is a potential problems with this specification?

# Clear, Unambiguous, Understandable

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  - ▶ The message must be triplicated. The three copies must be forwarded through three different physical channels. The receiver accepts the message on the basis of a two-out-of-three voting policy.
- What is a potential problems with this specification?
  - ▶ Can a message be accepted as soon as we receive 2 out of 3 identical copies, or do we need to wait for receipt of the 3rd

# Unambiguous, Validatable

- Specification fragment for an end-user program
  - ▶ The program shall be user friendly.
- What is a potential problems with this specification?

# Unambiguous, Validatable

- Specification fragment for an end-user program
  - ▶ The program shall be user friendly.
- What is a potential problems with this specification?
  - ▶ What does it mean to be user friendly?
  - ▶ Who is a typical user?
  - ▶ How would you measure success or failure in meeting this requirement?

# Unambiguous, Validatable

- Specification fragment for a linear solver
  - ▶ Given  $A$  and  $b$ , solve the linear system  $Ax = b$  for  $x$ , such that the error in any entry of  $x$  is less than 5 %.
- What is a potential problems with this specification?

# Unambiguous, Validatable

- Specification fragment for a linear solver
  - ▶ Given  $A$  and  $b$ , solve the linear system  $Ax = b$  for  $x$ , such that the error in any entry of  $x$  is less than 5 %.
- What is a potential problems with this specification?
  - ▶ Is  $A$  constrained to be square?
  - ▶ Can  $A$  be singular?
  - ▶ Even if the problem is made completely unambiguous, the requirement cannot be validated.

# Consistent

- Specification fragment for a word-processor
  - ▶ The whole text should be kept in lines of equal length. The length is specified by the user. Unless the user gives an explicit hyphenation command, a carriage return should occur only at the end of a word.
- What is a potential problems with this specification?



# Consistent

- Specification fragment for a word-processor
  - ▶ The whole text should be kept in lines of equal length. The length is specified by the user. Unless the user gives an explicit hyphenation command, a carriage return should occur only at the end of a word.
- What is a potential problems with this specification?
  - ▶ What if the length of a word exceeds the length of the line?

# Same Symbol/Term Different Meaning

- Can you think of some symbols/terms that have different meanings depending on the context?

# Consistent

- Language and terminology must be consistent within the specification
- Potential problem with homonyms, for instance consider the symbol  $\sigma$ 
  - ▶ Represents standard deviation
  - ▶ Represents stress
  - ▶ Represents the Stefan-Boltzmann constant (for radiative heat transfer)
- Changing the symbol may be necessary for consistency, but it could adversely effect understandability
- Potential problem with synonyms
  - ▶ Externally funded graduate students, versus eligible graduate students, versus non-VISA students
  - ▶ Material behaviour model versus constitutive equation

# Complete

- Internal completeness
  - ▶ The specification must define any new concept or terminology that it uses
    - ▶ A glossary is helpful for this purpose
- External completeness
  - ▶ The specification must document all the needed requirements
    - ▶ Difficulty: when should one stop?

# Incremental

- Referring to the specification process
  - ▶ Start from a sketchy document and progressively add details
  - ▶ A document template can help with this
- Referring to the specification document
  - ▶ Document is structured and can be understood in increments
  - ▶ Again a document template can help with this

# Traceable

- Explicit links
  - ▶ Within document
  - ▶ Between documents
- Use labels, cross-references, traceability matrices
- Common sense suggests traceability improves maintainability
- Shows consequence of change
- Minimizes cost of recertification
- Additional advantages
  - ▶ Program comprehension
  - ▶ Impact analysis
  - ▶ Reuse

# Accuracy Versus Precision



A



B



C



D

What is the distinction between accuracy and precision?

# Program Families

- Can think of general purpose (or multi-purpose) SC software as a program family
- Some examples of physical models are also appropriate for consideration as a family
- A program family is a set of programs where it makes more sense to develop them together as opposed to separately
- Analogous to families in other domains
  - ▶ Automobiles
  - ▶ Computers
  - ▶ ...
- Need to identify the commonalities
- Need to identify the variabilities
- Discussed in general in [12, 18]



# Background

- Program family idea since the 1970s (Dijkstra, Parnas, Weiss, Pohl, ...) - variabilities are often from a finite set of simple options [16, 17, 14]
- Families of algorithms and code generation in SC (Carette, ATLAS, Blitz++, ...) - not much emphasis on requirements [8, 34, 30, 6]
- Work on requirements for SC
  - ▶ Template for a single physical model [26, 25]
  - ▶ Template for a family of multi-purpose tool [21, 23, 22]
  - ▶ Template for a family of physical models [29, 28, 15]

# Motivation

- Requirements documentation
  - ▶ Allows judgement of quality
  - ▶ Improves communication
    - ▶ Between domain experts
    - ▶ Between domain experts and programmers
    - ▶ Explicit assumptions
    - ▶ Range of applicability
- A family approach, potentially including a DSL to allow generation of specialized programs
  - ▶ Improves efficiency of product and process
  - ▶ Facilitates reuse of requirements and design, which improves reliability
  - ▶ Improves usability and learnability
  - ▶ Clarifies the state of the art

# Advantages of Program Families to SC?

- Usual benefits
  - ▶ Reduced development time
  - ▶ Improved quality
  - ▶ Reduced maintenance effort
  - ▶ Increased ability to cope with complexity
- Reusability
  - ▶ Underused potential for reuse in SC
  - ▶ Reuse commonalities
  - ▶ Systematically handle variabilities
- Usability
  - ▶ Documentation often lacking in SC
  - ▶ Documentation part of program family methodology
  - ▶ Create family members that are only as general purpose as necessary
- Improved performance

# Is SC Suited to a Program Family Approach?

Based on criteria from Weiss [1, 32, 33, 13, 31]

- The redevelopment hypothesis
  - ▶ A significant portion of requirements, design and code should be common between family members
  - ▶ Common model of software development in SC is to rework an existing program
  - ▶ Progress is made by removing assumptions
- The oracle hypothesis
  - ▶ Likely changes should be predictable
  - ▶ Literature on SC, example systems, mathematics
- The organizational hypothesis
  - ▶ Design so that predicted changes can be made independently
  - ▶ Tight coupling between data structures and algorithms
  - ▶ Need a suitable abstraction

# Challenges

## 1. Validatable

- ▶ Requirements can be complete, consistent, traceable and unambiguous, but still not validatable
- ▶ Input and outputs are continuously valued variables
- ▶ Correct solution is unknown a priori
- ▶ Given  $dy/dt = f(t, y)$  and  $y(t_0) = y_0$ , find  $y(t_n)$

## 2. Abstract

- ▶ If too abstract, then difficult to meet NFRs for accuracy and speed
- ▶ Assumptions can help restrict scope, but possibly as much work as solving the original problem
  - ▶  $Ax = b$
  - ▶  $x^T Ax > 0, \forall x$
- ▶ Algorithm selection should occur at the design stage

# Challenges (Continued)

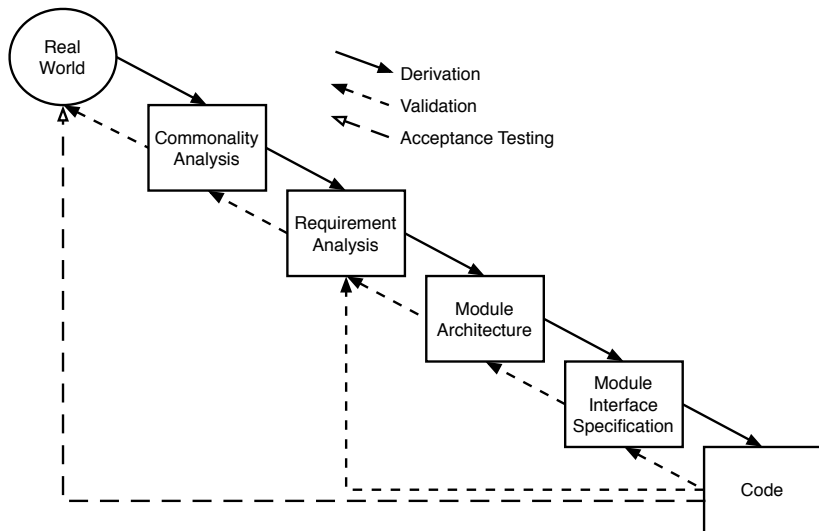
## 3. Nonfunctional requirements

- ▶ Proving accuracy requirements with a priori error analysis is a difficult mathematical exercise that generally leads to weak error bounds
- ▶ Context sensitive tradeoffs between NFRs can be difficult to specify
- ▶ Absolute quantitative requirements are often unrealistic

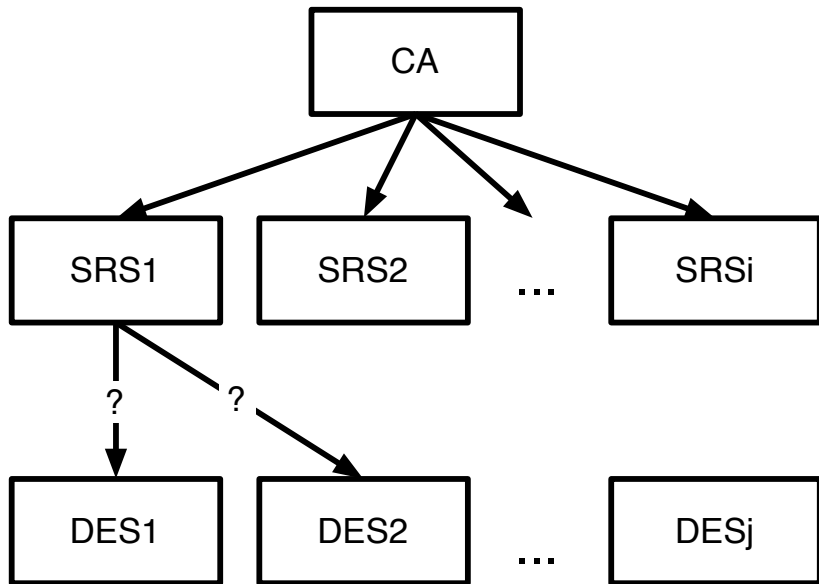
## 4. Capture and Reuse Existing Knowledge

- ▶ Cannot ignore the enormous wealth of information that currently exists
- ▶ A good design will often involve integrating existing software libraries
- ▶ Reuse software and the requirements documentation

# Overview of Process



# CA to SRS to Design





# Proposed Methodology

1. Identify family of interest
  - ▶ Specific physical model?
  - ▶ Multipurpose tool?
2. Commonality analysis
  - ▶ Terminology
  - ▶ Commonalities
  - ▶ Variabilities
  - ▶ Parameters of variation
  - ▶ Binding time
3. Domain Specific Language (DSL)
4. Generation of family members

# Commonality Analysis Template

From [21]

1. Reference Material: a) Table of Contents b) Table of Symbols c) Abbreviations and Acronyms
2. Introduction: a) Purpose of the Document b) Organization of the Document
3. General System Description: a) Potential System Contexts b) Potential User Characteristics c) Potential System Constraints
4. Commonalities: a) Background Overview b) Terminology Definition c) Goal Statements d) Theoretical Models
5. Variabilities: a) Input Assumptions b) Calculation c) Output
6. Traceability Matrix
7. References

# Abstract Requirements

- Appropriate level of abstraction by refining from goal to theory to input assumptions
- A goal is a functional objective the software should achieve:  
**G1:** Find the roots of an equation
- Goals are refined into theoretical models:  
**T1:** Given a function  $f(x)$  and an interval  $\{x | x_{lower} \leq x_{upper}\}$ , return the points where  $f(x) = 0$
- Introduce simplifying assumptions to allow theoretical model to be solved:  
**VA1,2:**  $f(x)$  is continuous on the interval and/or  $f(x)$  has at least one sign change on the interval

# Abstract Requirements (Continued)

- Each variability has an associated parameter of variation and a binding time
  - ▶ Specification time
  - ▶ Compile time
  - ▶ Run time

# Capture Existing Knowledge

- Systematic consideration from general to specific
- Communication between experts
- Standard template allows comparison
- Convenient framework for summarizing existing literature
- Eventually a library of requirements documentation
- CA refined by a family of SRSs

# System Requirements Specification (SRS)

- Based on IEEE Standard 830 and Volere requirements specification template
- Sections from CA are refined in SRS
- “Potential” descriptions are made specific
- Variabilities are set
- Binding times are set

# SRS Template

1. Reference Material
2. Introduction
3. General System Description
4. Specific System Description: a) Background Overview, b) Terminology Definition, c) Goal Statements d) Theoretical Models, e) Assumptions, f) Data Constraints, g) System Behaviour
5. Non-functional Requirements: a) Accuracy of Input Data, b) Sensitivity of the Model, c) Tolerance of Solution, d) Performance, ... i) Portability,
6. Solution Validation Strategies,
7. Other System Issues:
8. Traceability Matrix

# NFRs

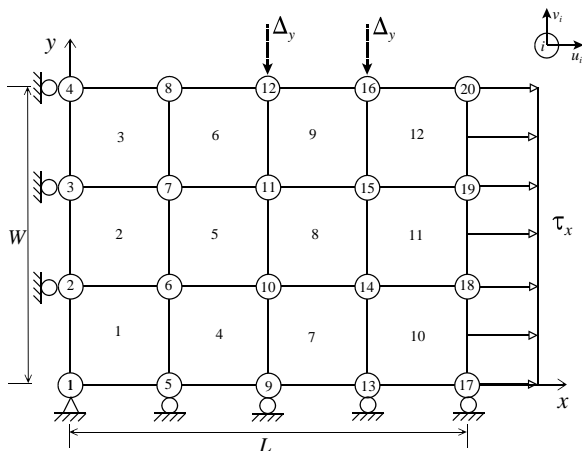
- Rather than absolute quantification of NFRs, use relative comparison between other program family members
- Specify requirements in big O notation
- Relative importance between NFRs using Analytic Hierarchy Process (AHP) [20]
  - ▶ Addresses challenge of comparing attributes that are measured in different (or hard to quantify) units
  - ▶ Series of pair-wise comparisons between attributes
  - ▶ 1 for equal importance, 3 for moderately strong importance, ..., 9 for extreme importance



# Validatable Requirements

- Relative comparison between programs is a validatable requirement
- Focus on a posteriori description, rather than a priori specification
- Solution validation strategies
  - ▶ Solve using different techniques
  - ▶ Identify benchmark test problems
  - ▶ Test cases built starting from assumed solutions (Method of Manufactured Solutions)
  - ▶ Partially validate for a simpler subset where the solution is known

# Mesh Generating Software



# Commonality Analysis for a Mesh Generator

From Chen's work [11, 23, 22]. Alternate approach in [5, 19, 2, 3, 4]

- Terminology
  - ▶ requirement
  - ▶ structured mesh, ...
- Commonalities
  - ▶ discretization
  - ▶ input from user is required, ...
- Variabilities
  - ▶ shape of elements
  - ▶ coordinate system used, ...
- Parameters of variation
  - ▶ line, triangle, quadrilateral, tetrahedral, hexahedral
  - ▶ Cartesian, polar, spherical, ...

# Definition of a Mesh

Let  $\Omega$  be a closed bounded domain in  $\mathbb{R}$  or  $\mathbb{R}^2$  or  $\mathbb{R}^3$  and let  $K$  be a simple shape, such as a line segment in 1D, a triangle or a quadrilateral in 2D, or a tetrahedron or hexahedron in 3D. A mesh of  $\Omega$ , denoted by  $\tau$ , has the following properties:

1.  $\Omega \approx \cup(K | K \in \tau : K)$ , where  $\cup$  is first closed and then opened
2. the length of every element  $K$ , of dimension 1, in  $\tau$  is greater than zero
3. the interior of every element  $K$ , of dimension 2 or greater, in  $\tau$  is nonempty
4. the intersection of the interior of two elements is empty

## Example Commonality

<b>Item Number</b>	C1
<b>Description</b>	A mesh generator discretizes a given computational domain (closed boundary $\Omega$ ) into a covering up of a finite number of simpler shapes.
<b>Related Variability</b>	V6, V8, V12, V14, V15, V16, V17, V18
<b>History</b>	Created - May 7, 2004

# Mesh Generator (MG) Goals

- G1 Input spatial domain  $\Omega$  output a mesh  $M$  that covers this domain.
- G2 Transform information on the materials, material properties and the locations of the different materials
- G3 Transform information on the boundary condition types, values and locations
- G4 Transform system information, such as numerical algorithm parameters

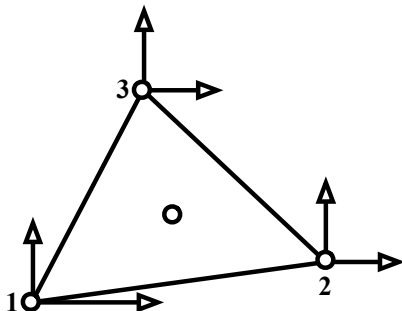
# Element Variability

Location of nodes: sequence of LocationT

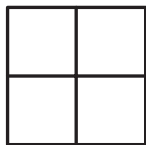
Number of dof at nodes: sequence of  $\mathbb{N}$

LocationT = tuple of  $(L_1 : \text{natT}, L_2 : \text{natT}, L_3 : \text{natT})$

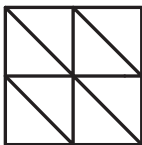
$\text{natT} = \{ s : \mathbb{R} \mid 0 \leq s \leq 1 : s \}$



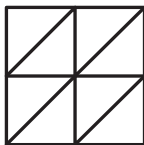
# Local Topology Variability



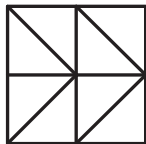
Quad



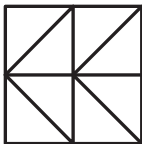
Triangle1



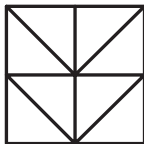
Triangle2



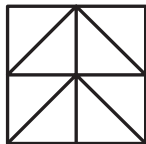
Triangle3



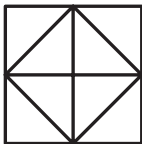
Triangle4



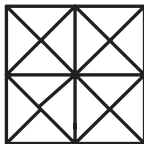
Triangle5



Triangle6



Triangle7



Triangle8



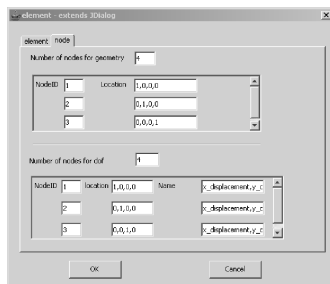
# DSL Using XML

```
<elementSet>
  <geometrySpec>
    <shape>triangle1</shape>
    <nodeGeo count="3">
      <node id="1">
        <location>1,0,0</location>
      </node>
      <node id="2">
        <location>0,1,0</location>
      </node>
      ...
    </nodeGeo>
  </geometrySpec>
</elementSet>
```

# Proof of Concept Implementation

From Cao's work [7, 27]

- XML document that customizes a Java object
- The Java object customizes the general purpose MG as it is loaded
- General purpose MG
  - ▶ All variabilities bound at run-time
  - ▶ Corresponds to an empty XML specification



# Linear Systems of Equations

$$Ax = b$$

Commonality analysis presented in [\[21\]](#)

# Goal and Theoretical Model

**G1:** Given a system of  $n$  linear equations represented by matrix  $A$  and column vector  $b$ , return  $x$  such that  $Ax = b$ , if possible

**T1:** Given square matrix  $A$  and column vector  $b$ , the possible solutions for  $x$  are as follows:

1. A unique solution  $x = A^{-1}b$ , if  $A$  is nonsingular
2. An infinite number of solutions if  $A$  is singular and  $b \in \text{span}(A)$
3. No solution if  $A$  is singular and  $b \notin \text{span}(A)$

# Variabilities for Input Assumptions

<b>Variability</b>	<b>Parameter of Variation</b>
Allowed structure $A$	Set of { full, sparse, banded, tridiagonal, block triangular, ..., Hessenberg }
Allowed definiteness $A$	Set of { not definite, positive definite, ..., negative semi-definite }
Allowed class of $A$	Set of { diagonally dominant, Toeplitz, Vandermonde }
Symmetry assumed?	boolean
Possible values for $n$	set of $\mathbb{N}$
Possible entries in $A$	set of $\mathbb{R}$
...	...

## Variabilities for Calculation

<b>Variability</b>	<b>Parameter of Variation</b>
Check input?	boolean (false if the input is assumed to satisfy the input assumptions)
Exceptions generated?	boolean (false if the goal is non-stop arithmetic)
Norm used for residual	Set of {1-norm, 2-norm, $\infty$ -norm }

# Variabilities for Output

<b>Variability</b>	<b>Parameter of Variation</b>
Destination for output $x$	Set of { to file, to screen, to memory }
Encoding of output $x$	Set of {binary, text }
Format of output $x$	Set of {arbitrary, ordered }
Output residual	boolean (true if the program returns the residual)
Possible entries in $x$	set of $\mathbb{R} \cup \{-\infty, \infty, \textit{undef}\}$

# Analytic Hierarchy Process

- Example 1
  - ▶ Embedded real-time system for digital signal processing
  - ▶  $n = 10$
  - ▶  $A$  is assumed to be Toeplitz

	<b>Speed</b>	<b>Accuracy</b>	<b>Portability</b>	<b>Priority</b>
<b>Speed</b>	1	3	5	0.64
<b>Accuracy</b>	1/3	1	3	0.26
<b>Portability</b>	1/5	1/3	1	0.11



# Solution Validation Strategies

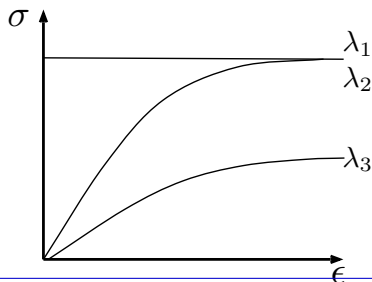
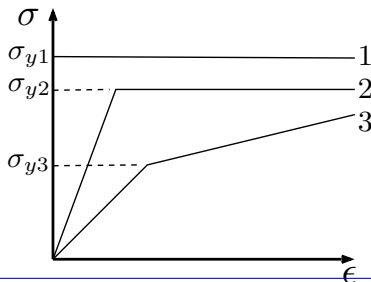
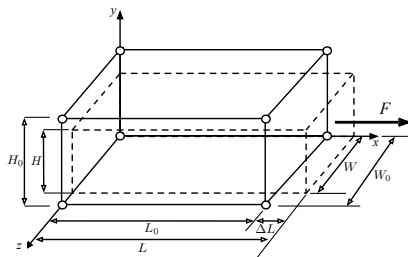
- Create test cases with known solutions
  - ▶ Assume  $A$  and  $x$ , calculate  $b$
  - ▶ Given  $A$  and  $b$  calculate  $x^*$  and compare to the assumed  $x$
- Comparison with Matlab
- Comparison with NAG library
- Where possible compare solution to interval arithmetic solution
- Experiments to describe how accuracy changes with increasing condition number

# Connection to Design

- Abstract requirements to concrete design decisions
- Reuse existing packages within the program family
- Summarize existing software by the parameters of variation and binding time
- If functional requirements match, then use NFRs
  - ▶ AHP to compare each design against each of the NFRs
  - ▶ Contribution of each NFR for each design alternative is found by multiplying the contribution of each alternative to the given NFR with the corresponding priority of that NFR
  - ▶ Sum the contributions
  - ▶ The highest overall score is the “winning” alternative

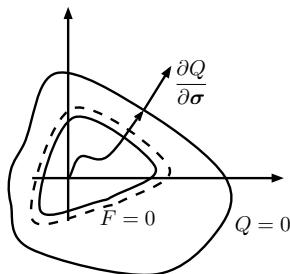
# A Family of Material Models

From McCutchan's work [10, 27, 28, 9, 29, 15]



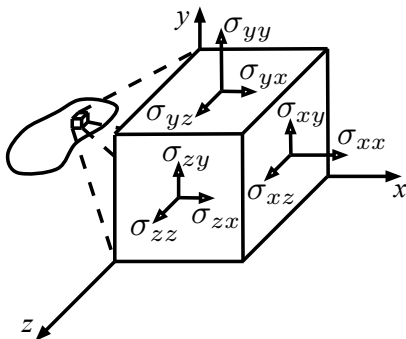
# Terminology Definitions

Label:	D_YieldFunction
Symbol:	$F = F(\boldsymbol{\sigma}, \kappa)$
Type:	$(\text{tensor2DT} \times \mathbb{R}) \rightarrow \mathbb{R}$
Related:	D_Stress, D_HardeningParameter
Sources:	...
Descrip:	The yield function defines a surface $F = 0$ in the six dimensional stress space ...



# Goal Statement

Label:	G_StressDetermination
Descrip:	Given the initial stress and the deformation history of a material particle, determine the stress within the material particle.
Refine:	T_ConstitEquation



# Assumptions

Label:	A_AdditivityPostulate
Related:	D_StrainRate
Equation:	$\dot{\epsilon} = \dot{\epsilon}^e + \dot{\epsilon}^{vp}$ with the following types and units $\dot{\epsilon}$ : tensor2DT (1/t) (1/s) $\dot{\epsilon}^e$ : tensor2DT (1/t) (1/s) $\dot{\epsilon}^{vp}$ : tensor2DT (1/t) (1/s)
Descrip:	The total strain rate ( $\dot{\epsilon}$ ) is assumed to decompose into elastic ( $\dot{\epsilon}^e$ ) and viscoplastic ( $\dot{\epsilon}^{vp}$ ) strain rates.
Rationale	This is a standard assumption for elastoplastic and elastoviscoplastic materials. The appropriateness of this assumption is born out by the success of theories built upon it.
Source:	[6, page 339]; [7, page 181]

# Theoretical Model

Label:	T_ConstitEquation
Related:	A_CauchyStress, A_DeformationHistory, A_PerzynaConstit, A_AdditivityPostulate, A_ElasticConstit, A_DescriptionOfMotion, V_MaterialProperties
Input:	$\sigma_0$ : tensor2DT (StressU) (Pa) $t_{begin}$ : $\mathbb{R}$ (t) (s) $t_{end}$ : $\mathbb{R}$ (t) (s) $\dot{\epsilon}(t)$ : $\{t : \mathbb{R}   t_{begin} \leq t \leq t_{end} : t\} \rightarrow$ tensor2DT (1/t) (1/s) $mat\_prop\_val$ : string $\rightarrow \mathbb{R}$ $E$ : $\mathbb{R}^+$ (StressU) (Pa) $\nu$ : poissonT (dimensionless)

# Theoretical Model Continued

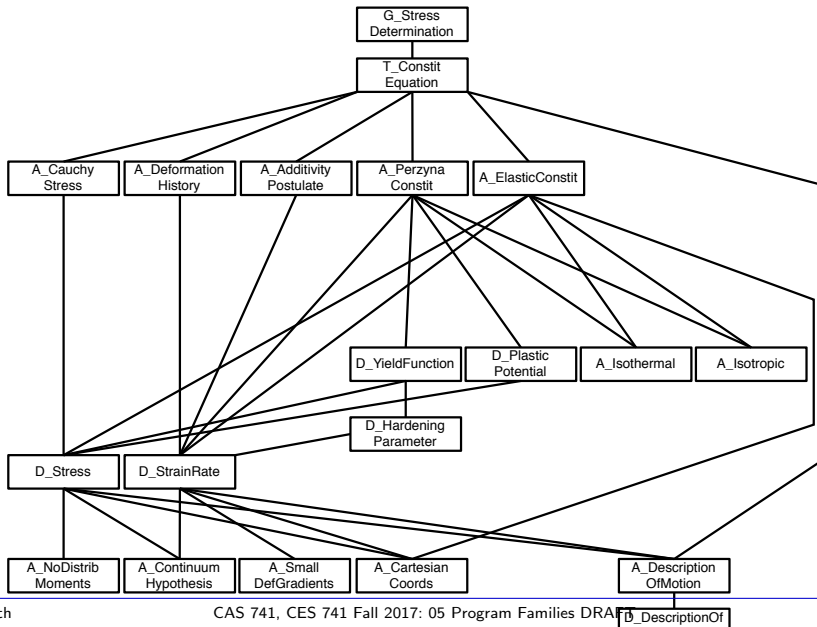
Label:	T_ConstitEquation
Output:	<p><math>\sigma(t) : \{t : \mathbb{R}   t_{begin} \leq t \leq t_{end} : t\} \rightarrow \text{tensor2DT}</math> such that</p> $\dot{\sigma} = \mathbf{D} \left( \dot{\epsilon} - \gamma < \varphi(F(\sigma, \kappa)) > \frac{\partial Q(\sigma)}{\partial \sigma} \right)$ <p>and <math>\sigma(t_{begin}) = \sigma_0</math>, the components of <math>\sigma</math> have the units of StressU (Pa)</p>
Derive:	The governing differential equation is found by first solving for $\dot{\epsilon}^e$ in A_AdditivityPostulate and then ...
Descrip:	The theoretical model is only completely defined once the associated variabilities (V_MaterialProperties) that define the material have been set. ...
History:	Created - June 14, 2007



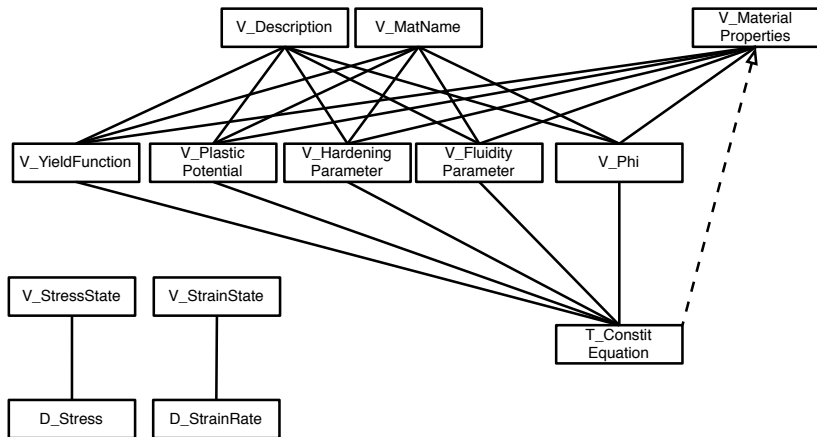
# Variabilities

- $F = F(\sigma, \kappa) : \mathbb{R}^6 \times \mathbb{R} \rightarrow \mathbb{R}$
- $Q = Q(\sigma) : \mathbb{R}^6 \rightarrow \mathbb{R}$
- $\kappa = \kappa(\epsilon^{vp}) : \mathbb{R}^6 \rightarrow \mathbb{R}$
- $\varphi = \varphi(F) : \mathbb{R} \rightarrow \mathbb{R}$
- $\gamma : \mathbb{R}$
- *mat\_prop\_names* : set of string

# Dependency Graph



# Dependency Graph Between Commonalities and Variabilities



## Example

Label:	E_StrainHardening
V_MatName	<i>name</i> = "Strain-Hardening Viscoelastic"
V_YieldFunct	$F = q\kappa^{\frac{n-1}{m}}$ (StressU) (Pa)
V_PlasticPot	$Q = q$ (StressU) (Pa)
V_HardParam	$\kappa = \epsilon_q^{vp}$ (L/L) (m/m)
V_Phi	$\varphi = F^{\frac{m}{n}}$ (StressU $^{\frac{m}{n}}$ ) (Pa $^{\frac{m}{n}}$ )
V_FluParam	$\gamma = nA^{\frac{1}{n}}$ (StressU $^{-m}$ t $^{-1}$ ) (Pa $^{-m}$ s $^{-1}$ )
V_MatProps	<i>mat_prop_names</i> = { "A", "m", "n" }, where the type of the material properties are ...
V_Description	<i>descript</i> = "This constitutive equation combines a power-law viscoelastic mate- rial with a strain hardening (softening) material. ..."

# Code Generation

- Specify variabilities
- Symbolically calculate terms needed by numerical algorithm, including  $\frac{\partial Q}{\partial \sigma}$ ,  $\frac{\partial F}{\partial \sigma}$ , etc.
- Symbolic processing avoids tedious and error-prone hand calculations
  - ▶ Reduces workload
  - ▶ Allows non-experts to deal with new problems
  - ▶ Increases reliability
- Use Maple Computer Algebra System for model manipulation
- Convert math expressions into C expressions using “CodeGeneration”
- Inline into a C++ class defining the material model
- A finite element program can this interface to realize the numerical algorithm

# BNF of DSL for $F$

$\langle expression \rangle \rightarrow \langle number \rangle |$

$(\langle expression \rangle) |$

$\langle expression \rangle ^ \langle expression \rangle |$

$\langle expression \rangle * \langle expression \rangle |$

...

$\langle simulation-variable-F \rangle | \langle user-defined-constants \rangle$

$\langle simulation-variable-F \rangle \rightarrow \mathbf{Kappa} | \langle simulation-variable-stress \rangle | \langle simulation-variable-stress-macros \rangle$

$\langle simulation-variable-stress \rangle \rightarrow \mathbf{SigmaXX} | \mathbf{SigmaYY} | \mathbf{SigmaZZ} | \mathbf{SigmaXY} | \mathbf{SigmaYZ} | \mathbf{SigmaXZ}$

$\langle simulation-variable-stress-macros \rangle \rightarrow \mathbf{Sxx} | \mathbf{Syy} | \mathbf{Szz} | \mathbf{Sxy} | \mathbf{Syz} | \mathbf{Sxz} | \mathbf{Sm} | \mathbf{J2} | \mathbf{J3} | \mathbf{q}$

$\langle user-defined-constants \rangle \rightarrow \langle string \rangle$

# Concluding Remarks

- Case studies of applying software engineering methodologies to mesh generating systems and linear solvers
- Appropriate and advantageous to apply program family strategy
- Challenges for software engineers
- General purpose scientific software is best studied as a program family
  - ▶ Variabilities are assumptions about problems that can be handled
  - ▶ Derive requirements from commonality analysis
- Eventually hope for automatic code generation

# Concluding Remarks (Continued)

A new methodology for documenting requirements for general purpose scientific computing software

## 1. Validatable requirements

- ▶ Relative comparison between program family members
- ▶ Focus on description rather than specification
- ▶ Solution validation strategy

## 2. Abstract

- ▶ Refine goal statement to theoretical model to input assumptions
- ▶ In some cases one may want to turn off input checking
- ▶ Connection to design



# Concluding Remarks (Continued)

## 3. NFRs

- ▶ Relative comparison
- ▶ AHP

## 4. Capture and reuse

- ▶ Systematic consideration from general to specific
- ▶ CA refined by a family of SRSs
- ▶ CA and SRS summarize existing knowledge and currently available software
- ▶ Standard template allows comparison
- ▶ Convenient framework for summarizing existing literature

# Concluding Remarks

- A new template for a family of models of physical phenomena
- Refinement of **Goals** to **Theoretical Models** using **Data Definitions** and **Assumptions**
- **Variabilities** are identified in the Theoretical Model
- A constitutive equation can be written using a (declarative) DSL and the code can be generated
- A DSL has been built, using Maple, for a virtual material testing laboratory

# Concluding Remarks

- SC software is a great candidate for development as a program family
- Produce programs that are as special or general purpose as needed
- Improve reusability, usability and reliability
- Potential to improve performance
- A commonality analysis facilitates the design of a DSL
- Symbolic processing and code generation are very useful techniques
- We will return to code generation later

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