

CAS 741 (Development of Scientific Computing Software)

Winter 2025

MIS Continued

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MIS Continued

- ADD STRATEGY DESIGN PATTERN
- Administrative details
- Questions?
- Review: Records, Libraries, ADTs, Abstract Objects, Generic ADTs
- Example - Student data
- Exceptions
- Quality criteria
- Modules with external interaction, enviro variables
- GUI modules
- ADTs
- Generic modules
- OO design spec
- Examples

Administrative Details: Report Deadlines

MG + MIS Week 10 Mar 19

Final Documentation Week 13 Apr 11

- The written deliverables will be graded based on the repo contents as of 11:59 pm of the due date
- If you need an extension for a **written** doc, please ask
- When ready, assign issues to your primary and secondary reviewers
- GitHub issues due two days after assignment deadlines
- From Drasil Code onward, Drasil projects no longer need to maintain traditional SRS

Administrative Details: Presentations

MG + MIS Week 10

Unit VnV/Implement Week 12

- Specific schedule depends on final class registration
- Informal presentations with the goal of improving everyone's written deliverables
- Time for presentation includes time for questions
- We will have to be strict with the schedule
- Presentations WILL be interrupted with questions/criticism; please do not take it personally
- Any concerns, let the instructor know

Presentation Schedule

- MG+MIS Present (L17, L18) (20 minutes)
 - ▶ **Mar 14: Ziyang, Aliyah, Yuanqi, Alaap**
 - ▶ **Mar 18: Phillip, Baptiste, Kiran, Volunteer?**

Presentation Sched Cont'd

- Implementation Present (L22 – L25) (20 min each)
 - ▶ Mar 28: Aliyah, Uriel, Ziyang, Yuanqi
 - ▶ Apr 1: Christopher, Bo, Joe, Junwei
 - ▶ Apr 4: Hussein, Kiran, Alaap, Qianlin
 - ▶ Apr 8: Yinying, Baptiste, Phillip

Presentation Schedule

- 3 presentations each
 - ▶ SRS everyone
 - ▶ VnV and POC subset of class
 - ▶ Design subset of class
 - ▶ Implementation or testing results everyone
- If you will miss a presentation, please trade with someone
- Implementation presentation could be used to run a code review, or code walkthrough

Admin Details Continued

- Summary of MIS Format and Notation
- Hoffman and Strooper

Questions?

- Questions on administrative details?
- Questions about Module Guide?
- Questions about upcoming presentation?
- Questions about MIS?
- Other questions?

Emphasis

- Math notation
- Modules with external interaction (environment variables)
- Types of modules
- Abstract Data Types (graph example)
- Qualities of an interface
- Design patterns
 - ▶ Adapter (Wrapper) pattern
 - ▶ Strategy pattern

MIS Continued Highlights

- SWHS example
- Mathematical notation example
- Quality criteria for your interface
- Generic modules (briefly)
- Inheritance (briefly)
- Operational versus descriptive specification

SWHS Example

- SWHS MIS
- Show decomposition by secrets
- Show uses relation
- Shows environment variables
- Specification parameters module
- Shows modules with external interaction
- Show use of abstraction (“such that”)

Examples of Modules: Abstract Data Type [2]

- What you are used to for OO programming
- Consists of a collection of abstract objects and a collection of procedures that can be applied to them
- Defines the set of possible values for the type and the associated procedures that manipulate instances of the type
- Encapsulates the details of the implementation of the type
- Multiple instances of the object
- Keyword **Template** in MIS
- Example
 - ▶ [Curve ADT Module](#)

Chemistry Example - Highlight Mathematics

- Problem Description
- Source Code
- Stoichiometry page 1
- Stoichiometry page 2

Quality Criteria [3, p. 83]

- Consistent
 - ▶ Name conventions
 - ▶ Ordering of parameters in argument lists
 - ▶ Exception handling, etc.
- Essential - omit unnecessary features
- General - cannot always predict how the module will be used
- As implementation independent as possible
- Minimal - avoid access routines with two potentially independent services
- High cohesion - components are closely related
- Low coupling - not strongly dependent on other modules
- Opaque - information hiding

Modules with External Interaction

- In general, some modules may interact with the environment or other modules
- Environment might include the keyboard, the screen, the file system, motors, sensors, etc.
- Sometimes the interaction is informally specified using prose (natural language)
- Can introduce an environment variable
 - ▶ Name, type
 - ▶ Interpretation
- Environment variables include the screen, the state of a motor (on, direction of rotation, power level, etc.), the position of a robot

External Interaction Continued

- Some external interactions are hidden
 - ▶ Present in the implementation, but not in the MIS
 - ▶ An example might be OS memory allocation calls
- External interaction described in the MIS
 - ▶ Naming access programs of the other modules
 - ▶ Specifying how the other module's state variables are changed
 - ▶ The MIS should identify what external modules are used

MIS for GUI Modules

- Could introduce an environment variable
- window: sequence $[RES_H][RES_V]$ of pixelT
 - ▶ Where $window[r][c]$ is the pixel located at row r and column c , with numbering zero-relative and beginning at the upper left corner
 - ▶ Would still need to define pixelT
- Could formally specify the environment variable transitions
- More often it is reasonable to specify the transition in prose
- In some cases the proposed GUI might be shown by rough sketches

Display Point Masses Module Syntax

Exported Access Programs

Routine name	In	Out	Exc
DisplayPointMassesApplet		DisplayPointMassesApplet	
paint			

Display Point Masses Module Semantics

Environment Variables

win : 2D sequence of pixels displayed within a web-browser
DisplayPointMassesApplet():

- transition: The state of the abstract object ListPointMasses is modified as follows:
ListPointMasses.init()
ListPointMasses.add(0, PointMassT(20, 20, 10))
ListPointMasses.add(1, PointMassT(120, 200, 20))

...

paint():

- transition *win* := Modify window so that the point masses in ListPointMasses are plotted as circles. The centre of each circles should be the corresponding x and y coordinates and the radius should be the mass of the point mass.

Specification of ADTs

- Similar template to abstract objects
- “Template Module” as opposed to “Module”
- “Exported Types” that are abstract use a ?
 - ▶ `pointT = ?`
 - ▶ `pointMassT = ?`
- Access routines know which abstract object called them
- Use “self” to refer to the current abstract object
- Use a dot “.” to reference methods of an abstract object
 - ▶ `p.xcoord()`
 - ▶ `self.pt.dist(p.point())`
- Similar notation to Java
- The syntax of the interface in C is different

Syntax Line ADT Module

Template Module

lineADT

Uses

pointADT

Exported Types

lineT = ?

Syntax Line ADT Module Continued

Routine name	In	Out	Exceptions
new lineT	pointT, pointT	lineT	
start		pointT	
end		pointT	
length		real	
midpoint		pointT	
rotate	real		

Semantics Line ADT Module

State Variables

s: pointT

e: pointT

State Invariant

None

Assumptions

None

Access Routine Semantics Line ADT Module

new lineT (p_1, p_2):

- transition: $s, e := p_1, p_2$
- output: $out := self$
- exception: none

start:

- output: $out := s$
- exception: none

end:

- output: $out := e$
- exception: none

Access Routine Semantics Continued

length:

- output: $out := s.dist(e)$
- exception: none

midpoint:

- output: $out :=$

$new\ pointT(avg(s.xcoord, e.xcoord), avg(s.ycoord, e.ycoord))$

- exception: none

rotate (φ):

φ is in radians

- transition: $s.rotate(\varphi), e.rotate(\varphi)$
- exception: none

Line ADT Local Functions

Local Functions

avg: $\text{real} \times \text{real} \rightarrow \text{real}$

$$\text{avg}(x_1, x_2) \equiv \frac{x_1 + x_2}{2}$$

Generic Modules

- What if we have a sequence of integers, instead of a sequence of point masses?
- What if we want a stack of integers, or characters, or pointT, or pointMassT?
- Do we need a new specification for each new abstract object?
- No, we can have a single abstract specification implementing a family of abstract objects that are distinguished only by a few variabilities
- Rather than duplicate nearly identical modules, we parameterize one **generic module** with respect to type(s)
- Advantages
 - ▶ Eliminate chance of inconsistencies between modules
 - ▶ Localize effects of possible modifications
 - ▶ Reuse

Generic Stack Module Syntax

Generic Module

Stack(T)

Exported Constants

MAX_SIZE = 100

Exported Access Programs

Routine name	In	Out	Exceptions
...

Stack Module Syntax

Exported Access Programs

Routine name	In	Out	Exceptions
s_init			
s_push	T		FULL
s_pop			EMPTY
s_top		T	EMPTY
s_depth		integer	

Semantics

State Variables

s : sequence of T

State Invariant

$$|s| \leq \text{MAX_SIZE}$$

Assumptions

$s_init()$ is called before any other access routine

Access Routine Semantics

`s_init()`:

- transition: $s := \langle \rangle$
- exception: `none`

`s_push(x)`:

- transition: $s := s || \langle x \rangle$
- exception: $exc := (|s| = \text{MAX_SIZE} \Rightarrow \text{FULL})$

`s_pop()`:

- transition: $s := s[0..|s| - 2]$
- exception: $exc := (|s| = 0 \Rightarrow \text{EMPTY})$

Access Routine Semantics Continued

`s_top()`:

- output: $out := s[|s| - 1]$
- exception: $exc := (|s| = 0 \Rightarrow \text{EMPTY})$

`s_depth()`:

- output: $out := |s|$
- exception: `none`

Stack Module Properties

$\{true\}$
 $s_init()$
 $\{|s'| = 0\}$

$\{|s| < MAX_SIZE\}$
 $s_push(x)$
 $\{|s'| = |s| + 1 \wedge s'[|s'| - 1] = x \wedge s'[0..|s| - 1] = s[0..|s| - 1]\}$

$\{|s| < MAX_SIZE\}$
 $s_push(x)$
 $s_pop()$
 $s' = s$

Object Oriented Design

- One kind of module, ADT, called class
- A class exports operations (procedures) to manipulate instance objects (often called methods)
- Instance objects accessible via references
- Can have multiple instances of the class (class can be thought of as roughly corresponding to the notion of a type)

Inheritance

- Another relation between modules (in addition to USES and IS_COMPONENT_OF)
- ADTs may be organized in a hierarchy
- Class B may specialize class A
 - ▶ B inherits from A
 - ▶ Conversely, A generalizes B
- A is a superclass of B
- B is a subclass of A

Template Module Employee

Routine name	In	Out	Except
Employee	string, string, moneyT	Employee	
first_Name		string	
last_Name		string	
where		siteT	
salary		moneyT	
fire			
assign	siteT		

Inheritance Examples

Template Module Administrative_Staff **inherits** Employee

Routine name	In	Out	Exception
do_this	folderT		

Template Module Technical_Staff **inherits** Employee

Routine name	In	Out	Exception
get_skill		skillT	
def_skill	skillT		

Inheritance Continued

- A way of building software incrementally
- Useful for long lived applications because new features can be added without breaking the old applications
- A subclass defines a subtype
- A subtype is substitutable for the parent type
- Polymorphism - a variable referring to type A can refer to an object of type B if B is a subclass of A
- Dynamic binding - the method invoked through a reference depends on the type of the object associated with the reference at runtime
- All instances of the sub-class are instances of the super-class, so the type of the sub-class is a subtype
- All instances of `Administrative_Staff` and `Technical_Staff` are instances of `Employee`

Dynamic Binding

- Many languages, like C, use static type checking
- OO languages use dynamic type checking as the default
- There is a difference between a **type** and a **class** once we know this
 - ▶ Types are known at compile time
 - ▶ The class of an object may be known only at run time

Point ADT Module

Template Module

PointT

Uses

N/A

Syntax

Exported Types

PointT = ?

Point ADT Module Continued

Exported Access Programs

Routine name	In	Out	Exceptions
new PointT	real, real	PointT	
xcoord		real	
ycoord		real	
dist	PointT	real	

Semantics

State Variables

xc: real

yc: real

Point Mass ADT Module

Template Module

PointMassT **inherits** PointT

Uses

PointT

Syntax

Exported Types

PointMassT = ?

Point Mass ADT Module Continued

Exported Access Programs

Routine name	In	Out	Exceptions
new PointMassT	real, real, real	PointMassT	NegMassExcep
mval		real	
force	PointMassT	real	
fx	PointMassT	real	

Semantics

State Variables

ms: real

Point Mass ADT Module Semantics

new PointMassT(x, y, m):

- transition: $xc, yc, ms := x, y, m$
- output: $out := self$
- exception: $exc := (m < 0 \Rightarrow \text{NegativeMassException})$

force(p):

- output:

$$out := \text{UNIVERSAL_G} \frac{self.ms \times p.ms}{self.dist(p)^2}$$

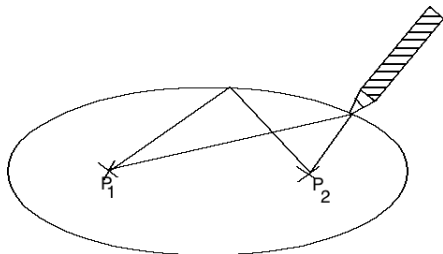
- exception: none

Classification of Specification Styles

- Informal, semi-formal, formal
- Operational
 - ▶ Behaviour specification in terms of some abstract machine
 - ▶ Not specifying how to implement, even though it looks this way
- Descriptive
 - ▶ Behaviour described in terms of properties
 - ▶ Prefer this because of its inherent abstraction
- The module state machine specification that we use is a mix of operational and descriptive specification - Why?

Example Operational Specification

- Specification of a geometric figure E
- E can be drawn as follows
 1. Select two points P_1 and P_2 on a plane
 2. Get a string of a certain length and fix its ends to P_1 and P_2
 3. Position a pencil as shown in the next figure
 4. Move the pen clockwise, keeping the string tightly stretched, until you reach the point where you started drawing



Example Descriptive Specification

Geometric figure E is described by the following equation

$$ax^2 + by^2 + c = 0$$

where a , b and c are suitable constants

Judging Appropriate Abstraction

- If an MIS is too abstract, it won't capture enough information for someone to do the implementation
- In some cases an MIS is not abstract enough
 - ▶ This can happen when someone is reverse engineering their spec from existing code
 - ▶ Can happen with an operational specification, as opposed to a descriptive specification
- Judge the abstraction level by
 - ▶ If a change in how your code works requires a change in your specification, look for a better abstraction
 - ▶ If writing and maintaining the spec is exceedingly frustrating, the spec could be too concrete
- The goal is to provide a descriptive, formal mathematical spec of everything, but at times we sacrifice this goal in the name of practicality

Examples

- Solar Water Heating System
- Measure Graduate Attributes
- Point Line and Circle
- Robot Path
- Vector Space
- Othello Program
- GIS
- Card Game Forty Thieves
- Generic 2D sequences
- Maze Formal Specification (Dr. v. Mohrenschildt)
- Mustafa ElSheikh Mesh Generator [1]
- Ahmed ElSheikh Mesh Generator
- Wen Yu Mesh Generator [4]

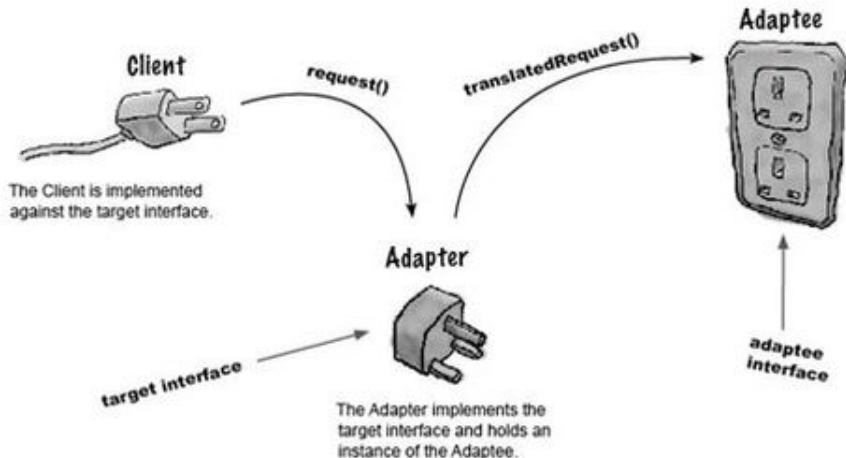
Implementing Your MIS

- The mapping between the MIS and the code is generally not “term” by “term”
- You do not need to use the mathematical type listed in the spec
- Consider A2 (Allocation to Engineering Programs) for set types
 - ▶ Problem Description
 - ▶ Source Code

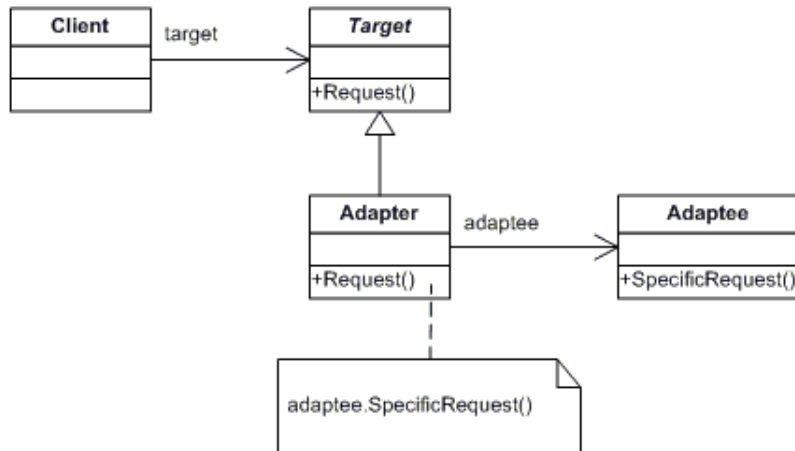
Design Patterns

- Christopher Alexander (1977, buildings/towns):
 - ▶ “Each pattern describes a problem which occurs over and over again in our environment, and then describes the core of the solution to that problem, in such a way that you can use this solution a million times over, without ever doing it the same way.”
- Design reuse (intended for OO)
- Solution for recurring problems
- Transferring knowledge from expert to novice
- A design pattern is a recurring structure of communicating components that solves a general design problem within a particular context
- Design patterns consist of multiple modules, but they do not constitute an entire system architecture

Adapter Design Pattern

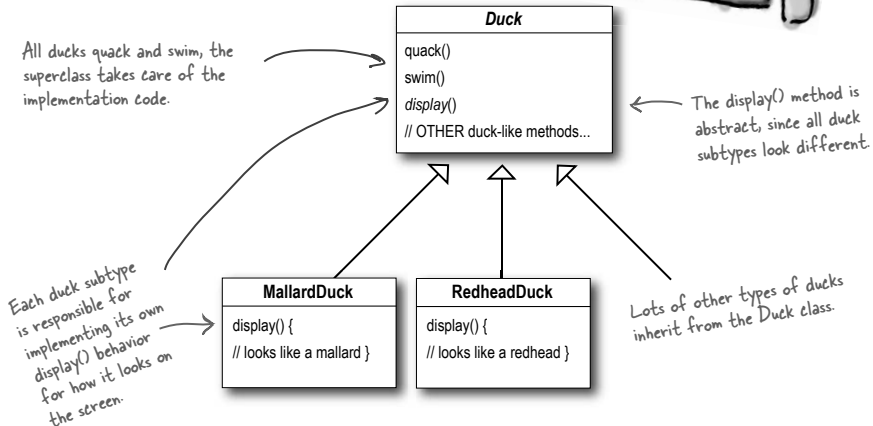


Adapter UML Diagram

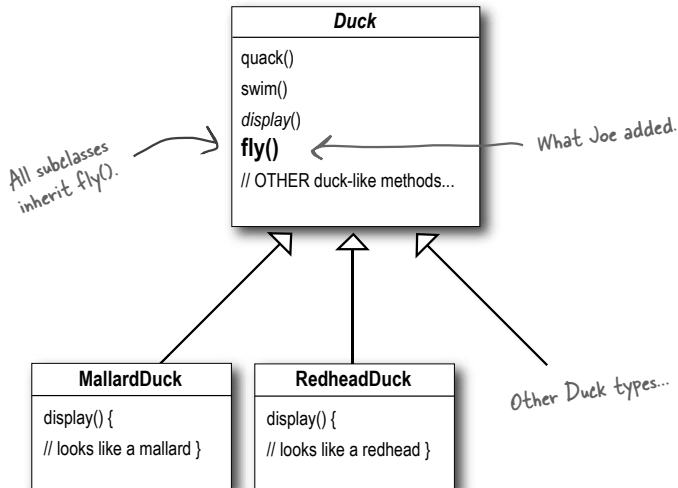


[Wikipedia entry](#)

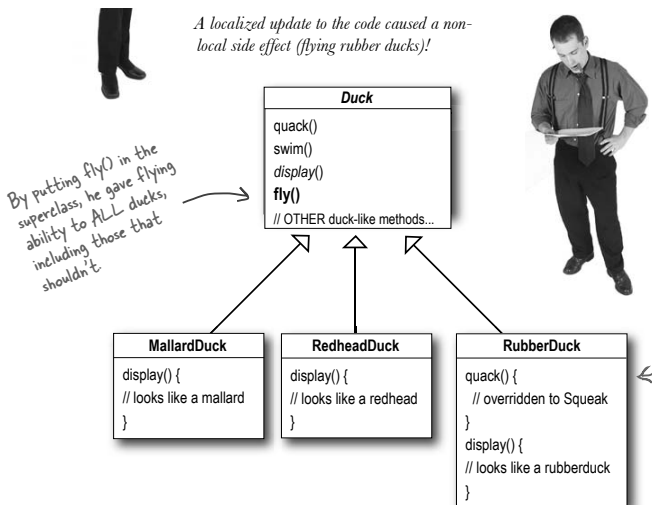
SimUDuck Example



Adding a Fly Method



Rubber Duck Problem



How to stop rubber ducks from flying?

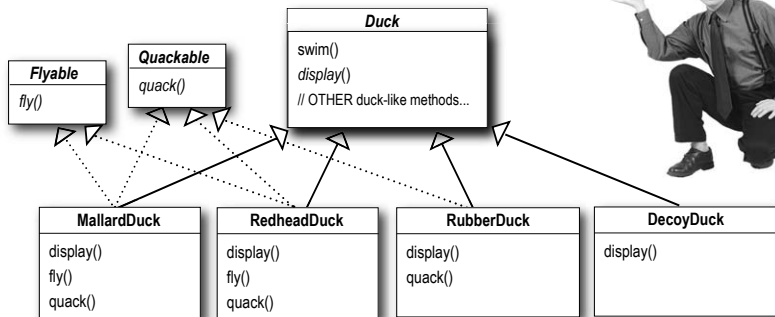
Rubber Duck Problem Continued

- Solve problem by overriding the fly() method to do nothing
- Not a good solution - think of the potential maintenance problems if we add wooden decoys, which cannot fly, or quack - what about different quacks?

Which of the following are disadvantages of using inheritance to provide Duck behaviour?

- A. Some code is duplicated across subclasses
- B. Runtime behaviour changes are difficult
- C. Difficult to gain knowledge of all duck behaviours
- D. Changes can unintentionally affect other ducks
- E. All of the above

How About an Interface?



Disadvantages of interface?

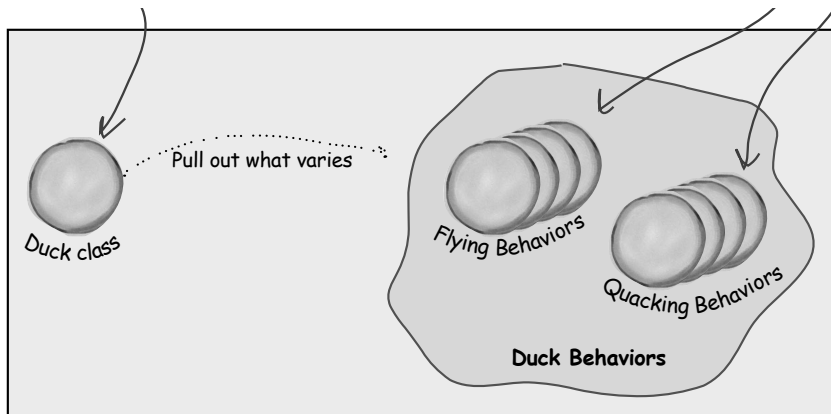
- A. Maintenance nightmare - the different options for fly and quack are duplicated everywhere
- B. Ducks that have fly and quack are clearly shown
- C. All of the above

Information Hiding

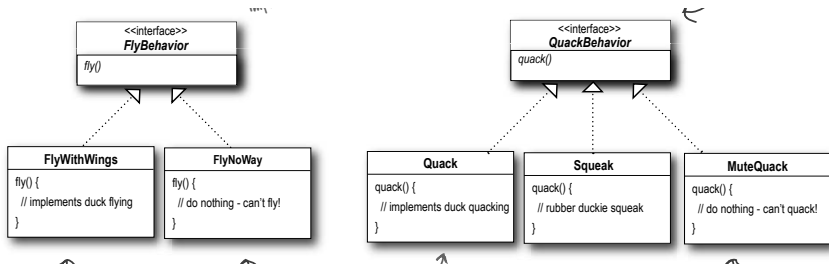
How can the principle of information hiding help us?

- A. Identify the aspects of the application that are likely to change and separate them from what is unlikely to change
- B. Provide a means for part of the system to vary independently of the other parts
- C. Prevent the program's user from knowing which ducks can fly and/or quack
- D. A and B
- E. A, B and C

Separate Out Changeable Parts (Likely Changes)



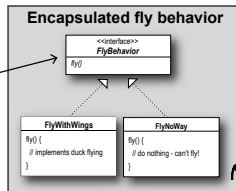
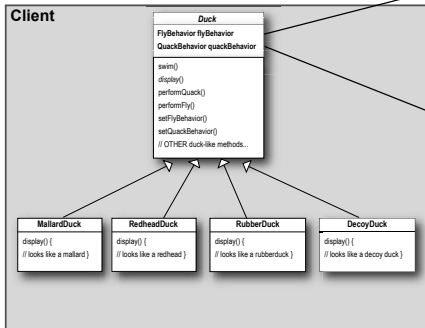
Implementing the Duck Behaviours



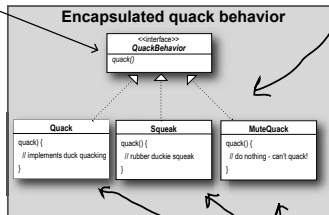
- Program to an interface not an implementation (interface in the sense we have used it for MISes, not just a Java interface)
- Other modules can use these behaviours too
- Can add new behaviours without touching the original Duck class

The Big Picture

Client makes use of an encapsulated family of algorithms for both flying and quacking.



Think of each set of behaviors as a family of algorithms.



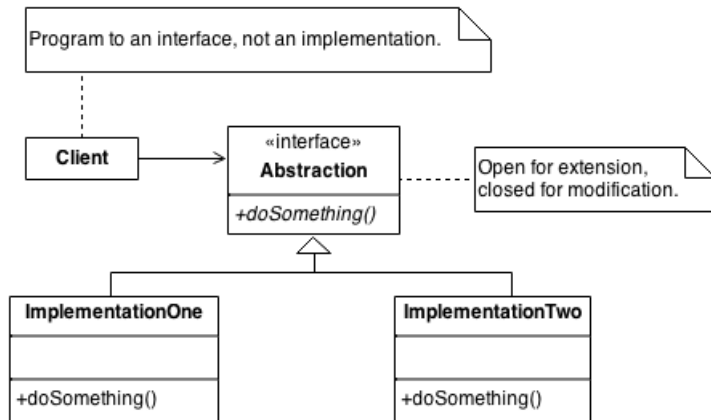
These behaviors "algorithms" are interchangeable.

Often Favour Composition over Inheritance

- Composition provides a “has a” relationship, as opposed to an “is a” relationship
- Composition provides greater flexibility
- Composition allows changing behaviour at runtime
- Many languages (like Java) do not allow multiple inheritance, but can have multiple compositions

Strategy Pattern

Defines a family of algorithms, encapsulates each one, and makes them interchangeable. Strategy lets the algorithm vary independently from the clients that use it.



References I



Jacques Carette, Mustafa ElSheikh, and W. Spencer Smith.

A generative geometric kernel.

In *ACM SIGPLAN 2011 Workshop on Partial Evaluation and Program Manipulation (PEPM'11)*, pages 53–62, January 2011.



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of a parallel mesh generation toolbox.
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